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Machining dispersions based procedures for computer aided process plan simulation

SAID HAMOU and ABDELMADJID CHEIKHJEAN MARC LINARESALI BENAMAR

Abstract. Among the whole manufacturing cycle of a product, a sequence of manufacturing stages needs to be optimized using the increasingly available computing resources. Computer aided process planning is seen as the missing link between CAD and CAM, which relates to the translation of design tolerances into manufacturing tolerances to be executed in the shop oor. A computerized module for process plan simulation, taking into account the manufacturing dispersions, has been developed. The process plan simulation program, which consists of three procedures, uses a combination of the minimal transfer method and a modi®ed form of the dispersions method. The ®rst procedure performs a veri®cation of the feasibility of the project's process plans through tolerance transfer. The second procedure performs an optimization of the tolerance distribution using the process capability data. The third procedure computes the manufacturing dimensions, which ensure the quality of the components and products. The simulation module has been validated on complex problems and shows that it gives good results in a short time. The manual work requires several days to solving this manufacturing problem.

1. Introduction

The last two decades have seen an enormous increase in the use of computers in industrial engineering activities. In fact, nowadays, computer resources can be exploited to speed-up and improve the accuracy of design, manufacture and assembly activities. Several stages of the manufacturing process of a product are therefore increasingly bene®ting, to different degrees, from this substantial computing power. However, despite the computerization of design

(CAD) and manufacturing (CAM) it is extremely dif®cult to ensure a communication between the two activities when several types of technological data are used, especially tolerances (Cheikh 1997). Computer aided process planning (CAPP) is sometimes seen as the missing link between CAD and CAM (Weill 1988, Halevi and Weill 1995). In fact CAPP can provide direct links to the design activity in terms of geometric de®nition and component attributes, such as functional dimensions and tolerances (Graves and Biscard 1999). At the same time it can create links towards the control and inspection activities of manufacture. Therefore, special attention is directed towards the analysis of manufacturing dimensions and tolerances, which ensure the quality of the product as dictated by the functional requirements. The process plan simulation, sometimes called manufacturing dimensions planning (see @gure 1), is a very dif@cult step to computerize in process planning. In fact the technical literature (Hamou 1998) shows that this procedure has been used manually and, in some cases, partially automated. Bourdet (1975) ®rst laid down the basis for process plan simulation based on the manufacturing process capabilities in terms of minimal machining dispersions. The simulation was performed manually as a tolerance transfer and optimization from design to manufacture. Taking into account the minimal machining dispersions, Duret (1981) proposed the minimal transfer method, which automates the veri®cation of the feasibility of a process plan. Fainguelernt et al. (1986) presented a computer program that automates the tolerance optimization procedure, starting from a data matrix of minimal reference dispersions. However, the program lacks any automated procedure for the feasibility check of the process plan and the solution to impossible tolerance transfer conditions prior to the optimization. This paper presents a programmed module that completely automates the process plan simulation of a manufacturing pre-project. The mini-

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Figure 1. Process plan simulation module.

mal transfer method and the machining dispersions method are combined in order to automate the process plan feasibility veri®cation. In addition, the paper proposes a modi®ed and programmable methodology, which integrates the veri®cation and optimization in the same procedure, starting with a data matrix of unknown dispersions instead of a data matrix of minimal reference dispersions. A comparison between the two methodologies is given in this paper.

2. Modelling of the process plan simulation

In order to automate completely the process plan simulation, a programmable methodology is proposed as a combination of the machining dispersions method introduced by Bourdet (1975) and the minimal transfer method introduced by Duret (1981). On one hand, these two methods are rebuilt so that they can solve any tolerance transfer problem. On the other hand, the methodology is built so that it can calculate an optimal distribution of the machining dispersions (capabilities) and @nally to compute optimal manufacturing dimensions and tolerances. The @nal simulation module is designed in the form of three chronological procedures. The @rst procedure performs a veri®cation of the manufacturing pre-project (A222 in @gure 1). The second procedure consists of the optimization of dispersions (A223 in @gure 1). The third procedure computes the @nal optimized manufacturing dimensions (A224 in @gure 1).

2.1. Fundamental dispersions model

If a machine is set up to execute a given operation in quantity production there are inevitably various uncontrollable stochastic factors that affect the ®nal size for the dimension I of a machined component. The measured sizes usually give a variation (scattering) DI called machining dispersion. It is the difference between the largest size I_n and the lowest size I_1 for a given batch as follows:

$$DI < I_n \ddot{y} I_1: -1f$$

These different dispersions will affect the process capability and consequently the manufacturing dimensions. They are usually due to localization and ®xture errors, machine rigidity and tool rigidity. The objective of the simulation is to verify the feasibility of the design speci®cations (dimensions BE) and the manufacturing conditions (dimensions BM) using a dispersions based fundamental model introduced by Bourdet (1975). In this model, for each phase in the process plan, the total dispersions Dl_i for a machined surface or Dl'_i for a positioning surface represents the positions occupied by surface i in relation to the machine referential system.

2.2. Procedure for the veri®cation of the pre-project based on minimal dispersions

The veri®cation of the process plan pre-project is carried out by checking the feasibility of the process plan with regards to the capabilities of the available manufacturing processes in the workshop. This condition is ful®lled when the manufacturing means can produce the design set dimensions imposed by the design of®ce. In technical terms, this condition is satis®ed when the tolerance interval (IT) of the design dimension BE is greater than or equals the manufacturing tolerance due to the summation of all dispersions Dl_i and is given as:

IT -dimension BE
$$f$$
 f DI $_{i}$: -2 f

In order to automate the task of the veri®cation using the minimal transfer method in conjunction with equation (2), the manufacturing pre-project of a sample, an example of which is shown in ®gure 2 for a mechanical part, is written in a matrix format of $I_{\rm p}$ lines and I_s columns. Figure 3 highlights a sample veri@cation sequence for design dimension BE = 16 + 0.6. In this @gure, I_s represents a surface varying between 1 to 8 and Ip represents a phase varying between 1 to 5. The element A (I_p, I_s) of the initial matrix contains a dispersion value only when surface I_s intervenes in phase I_p as a machined surface (DI) or as a positioning surface (Dl', Dl", Dl", ...) in an subsequent phase. Otherwise the value is set to zero. The manufacturing tolerance interval given by SDl_i is computed using the method of minimal transfer and is then compared to IT, the tolerance interval of the design dimension (BE). This method is explained in the sample example of [®]gure 3 and the ⁻owchart steps of ®gure 4. The veri®cation procedure is carried out for each design dimension (BE) by successive elimination of the dispersions from single element columns and lines, except for columns whose surfaces are limits to a design dimension (BE). In fact, on one hand, columns (surfaces) with one dispersion DI are eliminated because they are not taking part in the localization of a surface. On the other hand, lines (phases) having



Figure 2. Sample example of a mechanical part pre-project.

PH 00 Δl_1 Δl_2 Δl_3 Δl_4 <th< th=""><th></th><th>1</th><th>2</th><th>3</th><th>4</th><th>5</th><th>6</th><th>7</th><th>8</th></th<>		1	2	3	4	5	6	7	8				
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	PH 00	AL	-	AL.		<u> </u>	AL	, ,	AL				
Difference Difference Difference Difference PH200 Δl_2 Δl_1^{**} s Δl_2^{**} PPH300 Δl_2 Δl_1^{**} s Δl_2^{**} PPH300 Δl_2 Δl_1^{**} s Δl_2^{**} Sand cast part $\Rightarrow \Delta l_1 = \Delta l_2 = \Delta l_3 = \Delta l_4 = 0.5$ Preproject verification for dimension BE = 16 ± 0.6 Pre-project verification for dimension BE : $l^{1**} = 1$, $m = 2$, $lT = 1, 2$ Folerance analysis for dimension BE : $l^{1**} = 0$ $l^{1**} = 2$, $lT = 1, 2$ Folerance analysis for dimension BE : $l^{1**} = 2$, $lT = 1, 2$ Folerance analysis for dimension BE : $l^{1**} = 2$, $lT = 1, 2$ Folerance analysis for dimension BE : $l^{1**} = 2$, $lT = 1, 2$ Folerance analysis for dimension BE : $l^{1**} = 1$, $m = 2$, $lT = 1, 2$ Folerance analysis for dimension BE : $l^{1**} = 1$, $m = 2$, $lT = 1, 2$ Folerance analysis for dimension BE : $l^{1**} = 1$, $m = 2$, $lT = 1, 2$ Folerance analysis for dimension BE : $l^{1**} = 1$, $m = 2$, $lT = 1, 2$ Folerance analysis for dimension BE : $l^{1**} = 1$, $m = 2$, $lT = 1, 2$ Folerance analysis for dimension BE : PH200 D Δl_1^{**} Fole	PH100	AP.			-	AL							
$\begin{array}{c c c c c c c c c c c c c c c c c c c $	PH200				AL	AL.							
10000 $\Delta J_1 = \Delta J_1 = \Delta J_2 = \Delta J_3 = \Delta J_3$ PH400 $\Delta J_1 = \Delta J_1 = \Delta J_3 = \Delta J_3 = 0.5$ Sand cast part $\Rightarrow \Delta J_1 = \Delta J_1 = \Delta J_3 = \Delta J_3 = 0.5$ Mounting drilling $\Rightarrow \Delta J_2 = 0.07$ etc Pre-project verification for dimension BE = 16 ± 0.6 Inputs : $l = 1$, $m = 2$, $lT = 1, 2$ Following cleanest columns to zero except l and m : l^{10} - Set single element columns to zero except l and m : I 2 3 4 5 6 7 8 PH00 ΔJ_1 0 $\Delta J_1^{m_1}$ $\Delta J_1^{m_2}$ $\Delta J_1^{m_2}$ D PH200 ΔJ_2 $\Delta J_1^{m_2}$ D D D Q^{11} Q ΔJ_2 $\Delta J_1^{m_2}$ D Q PH200 ΔJ_2 $\Delta J_1^{m_2}$ D Q Q Q^{11} Q ΔJ_2 $\Delta J_1^{m_2}$ Q Q PH200 ΔJ_2 $\Delta J_1^{m_2}$ Q Q Q Q^{11} Q Q Q Q Q	PH300		AL			Al ¹¹ ,							
PH 00 $\Delta l_1 = \Delta l_2 = \Delta l_2 = 0.5$ Notating drilling $\Rightarrow \Delta l_2 = 0.07$ etc Pre-project verification for dimension BE = 16 ± 0.6 inputs : $l = 1$, $m = 2$, $lT = 1, 2$ For encode analysis for dimension BE : $l^{10} - Set single element columns to zero except l and m$: 1 2 2 4 5 6 7 8 1 2	PH400				-	Al"",		AL					
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1 2 3 4 5 6 7 8 PH 00 Δl_1 0 0 0 0 0 PH 00 Δl_1 0 Δl_5 - - 0 0 PH 00 Δl_1 0 Δl_5 - - 0 0 0 PH200 0 Δl_5 - - <t< td=""><td colspan="11">Tolerance analysis for dimension BE :</td></t<>	Tolerance analysis for dimension BE :												
1 2 3 4 5 6 7 8 PH 00 ΔI_1 0 0 0 0 PH100 ΔI_1 0 ΔI_5 - - PH200 0 ΔI_5 - - - PH300 ΔI_2 ΔI^{**}_5 - - - PH400 ΔI^{**}_5 0 - - - - PH400 ΔI^{**}_5 0 - - - - - PH400 ΔI^{**}_5 0 - - - - - PH00 0 ΔI^{**}_5 0 - - - - PH100 ΔI^{*}_5 ΔI^{**}_5 - - - - - - PH200 0 0 - - - - - - - - - - - - - -	1 ⁽⁰ - Set single element columns to zero except I and m :												
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PH100 Δl_1 Δl_5 PH200 0 0 PH300 Δl_2 Δl^{**}_5 PH400 0 0 Minimal transfer satisfied. $\Sigma \Delta l_1 = (\Delta l^*_1 + \Delta l_5) + (\Delta l^*_5 + \Delta l_2) = (0,5 + 0,05) + (0,03 + 0,05) = 0,63$ $\lambda (3 < 1, 2 = IT BE$ Pre-project is verified for this design dimension	PH 00	0											
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Minimal transfer satisfied. $\sum \Delta i = (\Delta i_1 + \Delta i_5) + (\Delta i_5 + \Delta i_2) = (0,5 + 0,05) + (0,03 + 0,05) = 0,63$ 0,63 < 1,2 = IT BE Pre-project is verified for this design dimension		PH400 0											
$\sum \Delta li = (\Delta l_1^* + \Delta l_5) + (\Delta l_2^* + \Delta l_2)=(0,5 + 0,05) + (0,03 + 0,05)=0,63$ $\lambda 63 < 1,2=1T BE$ Pre-project is verified for this design dimension	PH400												
0.63<1,2=ITBE Pre-project is verified for this design dimension	PH400 Minimal	transfer	satisfied										
Pre-project is verified for this design dimension	PH400 Minimal CAli = (2	transfer $\Delta_1^* + \Delta_2^*$	satisfied	5+Al2)-	-(0,5+0	0,05) + (0,	,03 + 0,0)5)=0,63					
	РН400 Minimal EAli = (/),63<1,2	transfer M ¹ 1 + M	satisfied _) + (Δl~	s + Δl ₂)	-(0,5+0	0,05) + (0,	,03 + 0,0	05)=0,63					

Figure 3. Veri®cation example of dimension BE = 16 + 0.6.

only one dispersion DI are eliminated because a phase needs at least two dispersions DI, one for the machined surface and another for the positioning surface. This elimination process is carried out until the minimal transfer condition is satis®ed, which is the presence of zero DI or two DI per column, except for surfaces that are limits to the design dimension (BE). At the end, we verify equation (2) by summing all the remaining Dl_i dispersions in the matrix.

In the case when equation (2) is not satis®ed, the pre-project is not veri®ed. The tolerance transfer is impossible. This problem can be solved in three ways. The ®rst solution consists of changing the tolerance interval IT for the design functional dimension (BE). This decision is the responsibility of the design of®ce. The second one involves changing datum elements and reference planes, which means changing the rooting and operations sheets of the whole process plan. This solution means rewriting a new process plan pre-project. The third solution is more adequate and consists of diminishing the IT of one or more manufacturing dimensions (CF) in the tolerance chain that makes up the IT of the design dimension as given by



Figure 4. Flowchart of the veri®cation procedure.

equation (2). Based on minimal reference dispersions for different processes, which are usually given by experience (Hamou 1998), this solution is based on a successive diminution of the dispersions Dl_i (DB_i for raw material dispersions) without going under any known minimal reference value.

2.3. Procedure for the optimization of dispersions

2.3.1. Optimization based on the minimal dispersions. Once the pre-project has been veri®ed and retained, the manufacturing tolerance intervals can be computed. To do this, we build an optimization matrix $B(I_c,$

 I_d) of p lines and q columns where p represents the number of design dimensions and manufacturing dimensions and q the number of dispersions. The ®rst table of ®gure 5 contains this matrix (column 3 to column 12) corresponding to the mechanical part of ®gure 2. Each column represents a dispersion DI which is affected by a surface beginning with the ®rst one, the second one and so on. Then we compute the residuals ε given by the following equation:

e < IT -dimension BE
$$f$$
 \ddot{y} DI $_{i}$: -3 f

x z

After the initial distribution matrix has been built and the residuals e computed, we determine the processing order of the lines in this matrix depending on the values of these residuals. This order is given by the increasing values of the residuals. As explained in @gure 5, this optimization process consists of an equal

O pti	Optimization and distribution data matrix for dispersions																	
Line	Dim	-M1	ΔΓ ₁	M ₂	-N ₃	584	<i>.M</i> ₂	Mr.	Al''3	M ,	Δl_{+}	N ₂	<i>3</i> 4	n	ΣAli	6	donc	1
1	1-2	-	0.5	0.05	-		0.05	-	0.03	-		-	-	1.2	0.63	0.57		1
2	2.5		-	0.05				-	0.63					0.2	0.08	0.12		
-	3.7	· ·	•		· ·		· ·			0.03	•	0.07	•	0,2	0.10	0.10	-	4
÷	2-4	-	- 0.5	0.05	-	0.05	0.05	0.05	0.05	- 0.03		- 0.07	- 0.5	0.5	1.65	0.34	-	4
-	3.4	0.5	0.5	<u> </u>	0.1	0.05	0.05	0.03	<u> </u>	0.05		0.07	0.5	0	1.63		-	•
7	3.6	0.5	0.5		1		0.05				0.5			0	1.55		-	1
Distri	Distribution order for lines is : 3 - 2 - 4 - 1 Step 1 :																	
Line	Dim	Ab	AL:	Ab	Ab.	A.	Ale	AL.	Al	N°"-	AL	Alt	Ale	IT.	5.36			s/n
1	5.7									0.03	1.00	0.07	1.00	0.2	0.10	0.10	2	0.05
											-	-	-					
Line	Dim	- 341	- Al' 1	-542	- 58 ₀	-54.6	- 345	51'5	Al ⁻⁵	01°*s	-346	Δŀ	Δl_{0}	п	ΣMi	6		ic/n
	1.7					_		-		ept.	+	opt.		0.2	0.5		_	_
/	347		,					,		0.03		0.12		0.2	0.2	0		
Step	Step 2 :																	
Line	Dim	Δl_1	$\Delta \Gamma_1$	-M2	Δk_0	-Ma	-245	<i>8</i> 1 '5	ΔI~,	APT,	- 246	Δŀe	-144	п	2.56	6		ic'e
2	2.5			0.05					0.03	ept.	+ -	opt.	÷ .	0.2	0.08	0.12	2	0.06
-	8.7			0.00							-			9.4	0.00	5.14		0.00
Line	Dim	<i>M</i> 1	Δľ'1	스타 opt.	-Mg	M_4	Δ,	ы,	۵ľ*s opt	പ്"ം ept.	-M ₆	Δl ₂ opt.	-54.8	π	ΣM	6	*	c/a
2	2-5	-	-	0.11	-		-	•	0.09	-		-	-	0.2	0.2	-0		-
Step	3:																	
Line	Dim	Δh	$\Delta \Gamma_1$	스타 opt.	Δb_0	34	Δ1,	<i>M</i> ',	ΔI"s ept.	Al"s opt	.M.,	Δh opt.	Δl_{8}	п	ΣMi	6		e,µ
4	2-4			0.11		0.05		0.03	0.09		· ·			0.5	0.28	0.22	2	0.11
	10 m		1.07						1.178		1.0	1	1	1	1 27 A.U.			-
Line	U.S.	24	20.1	3b	28)	214	265	AF9.	0.075	AF 9	- 24	0.05	- 244		2.00	°	· 1	6/B
1	2-4			0.11		0.16		0.14	0.07		+ ·		<u> </u>	0.5	0.5	0		
Step	4:												_	_	_		_	
Line	Dim	Δh	$\Delta \Gamma_1$	Δb	Δb_2	ΔI_{0}	-245	$\Delta \Gamma_{3}$	ΔT_{β}	AF	- Ma	Δb	-144	п	ΣMi	6		6' 9
<u> </u>	1.5		0.5	opt.		ept.	0.05	opt,	ept.	ept.	+	opt.		1.5	0.75	0.45	-	0.33
Ĺ	154		0.5	w.11			0.05		0.07				· ·	1.4	0.75	0.45		0.22
Line	Dim	Δl ₁	ΔΓ ₁ opt.	Ab opt.	Δl_0	∆l _i opt	Δlş opt.	ΔΓ ₃ opt	∆l"s ept.	Al ^{ra} s opt	.M ₆	Δh opt.	Δl_{8}	п	ΣMi	6	*	©'8
1	1-2		0,72	0.11	-		0.27		0.09					1.2	1.2	0		
After	After computation, optimized dispersions are :																	
0.5		0.725	0.1	11	0.5		16	0.275		0.14	0.0	5	0.08	0	~	0.12		0.6
Final	distri	ibutio	n mat	trix fi	or dis	nersio	uns 1	0.210			0.0		0.00			0.14		
	- Di-	41	1 100	1.0		100		1.00	1.000	1.07 ⁻¹⁰	12			17	N - 1		dene	1
Ling	LNB .	<i>Δ</i>)	0.73	<u>Ab</u>	Δb	34	Als 0.37	ar,	AC3	A 3	<i>3</i> 4	Ah)	a,	11	2.06	6	0080	
1	3.4		0.72	0.11	-		0.27		0.09	÷.		1		0.2	0.2	0	Yes	
-	3.7	-			<u>.</u>		÷.	÷.		0.08		0.12		0.2	0.2	0	Ya	1
4	2.4		-	0.11	-	0.16	-	0.14	0.09	-		1	-	0,5	0.5	0	Yes	1
5	7-8	0.5	0.72				0.27			0.08		0.12	0.6	Û	2.3	•		1
6	3-4	0.5	0.72	•	0.5	0.16	0.27	0.14		•				0	2.3			
7	3-6	0.5	0.72				0.27				0.5			0	2]

Figure 5. Classical optimization procedure for the sample example.

distribution of each residual e on the dispersion elements Dl of each line in the matrix so that the following equation is satis®ed:

IT -dimension BE
$$f < DI_i$$
: -4 f

After processing a line, the optimized elements of the matrix are saved and their values are memorized

before going to the next line. The tolerance intervals are updated during this process using the optimized dispersions from the previously processed ones. Figure 5 gives the optimization results for the sample example of @gure 2.

2.3.2. Optimization based on unknown dispersions. A modi®ed form of the dispersions method (Marty

Dispe	Dispersions data matrix for simultaneous optimization and verification														
Line	Dan	1.44	AL.	1.51.	AL.	AL.	1.44	AL.	10175	A	1.44	LAb.	44	II.m.	٦.
1	1-2	0	85	X:	0	0	1.	0	10	0	0	0	0	1.2	
2	2.5	0	0	~ 10	0	0	0	0	15	0	0	0	0	0.2	-
,	5-7	0	0	0	9	0	0	0	0	x''',	0	X)	0	0,2	1
4	24	0	0	x)-	9	54	0	8')	1°) -	0	0	0	0	0,5	1
5	7-8	x _i	8'1	0	0	0	xj	0	0	x,	0	X 2	14	mini	1
6	34	x_i	x')	0	x,	X _F	x ₂	8'1	0	0	0	0	0	mini	1
7	5-6	x _F	X9	0	0	0	X)	0	0	0	X _E	9	0	en.m.	1
Distri	hutica	a orde	r for li	ines is	. 2 _	3-4	- 1		_					-	
Sen L:	oution	TOTOL	1011	11165 15		3-4	- 1								
Lise	Dim	.14.	AP.	34	Ab.	14	.11.	M.	41.5	A!	.11	14	44	ILau	7
2	2.5	0	6		6	0	0	0	100	6	0	0	0	0.2	-
Ľ				~			1.		- /	1.					1
Line	Dan	34,	۵Ľ,	342	Als.	34	24,	Ш,	۵, الد	<i>a</i> ,	34,	24,	34g	IT _{CHL}	k, .
2	2-5	0	0	0,1	0	0	0	0	0,1	ð	0	0	0	0,2	0,1
Step 2 :	·					· · ·		·	-	· · · ·		·	<u> </u>		<u> </u>
Line	Dan	34	ΔT_{1}	34;	26	3he	24,	ыr,	<i>41 °</i> ,	<i>a</i> ,	34	劫	3h	IT _{ON}	1
3	5-7	0	0	0	9	0	0	0	0	x,	0	æ	0	0,2	1
						-	-		-						-
Linc	Dan	34	Δl')	38)	Als .	3h	289	Ш,	ai *,	ы,	ᅶ	2h	3h	IT _{CH}	k;
3	5-7	0	0	0	9	0	0	0	0	9,1	0	0,I	0	0,2	0,1
Step 3 :		1				1	L.								
Line	Dan	34	<i>8</i> °1	alı,	243	34	24,	ar,	ar.,	<i>ы</i> ,	34,	3h	ille A	II CHL	4
·	24	Ŷ	Ψ	10	÷	54	ů.	<i>K</i> 1	<i>x</i> ,	Ψ.	°	°	v	0,5	1
Line	Dan	24	<i>M</i> ',	36	<i>M</i> ,	34,	24.	ar.	۵, ال	A ,	34	<i>.2</i> .	34	IT _{CH}	<i>k</i> ,
4	2.4	0	0	0,1	0	0,15	0	0,15	0,1	0	0	0	0	0.5	0,15
Step 4 :							-								
Line	Dan	34,	۵Ľ ,	382	Als .	3hi	24,	Шs,	ai *,	₩…,	34,	20	3hj	IT _{CHL}	1
1	1-2	0	87	x2	9	0	X)	0	17	0	0	0	0	1,2	1
Line	Dun	-Mi	<i>M</i> '1	2 4 2	<i>N</i> 3	∆k,	<i>M</i> ,	м,	Al *,	<i>≌</i> ,	24	<i>M</i> 1	<u>54</u>	псн	<i>k</i> 4
<u>'</u>	1-2	0	0,5	0,1	0	0	0,5	0	0,1	0	0	0	0	1,2	0,5
After	comp	utatio	n, opt	imize	d disp	ersio	ns are	:							
Al. or	<i>M</i> .	n 4	1	يور واث		- 1	يو. 10	ΔΓr.m.	41%	-	1	the sec	Alt.		Maran.
0,5	0.5	0	1	0,5	0,15		1.5	0,15	0,1	- 4	1	4.5	0,1	-	3.5
						_			_	_			_		
Final d	listribu	tion ma	trix for	disper	sions										
Line	Dan	<i>3</i> 4	δľ'1	8 4 2	Al3	584	513	SI's	81°,	a,	54	80	54 <u>6</u>	IT _{CH}	1
1	1-2	0	0.5	0,1	0	0	0.5	0	0,1	0	0	0	0	1.2	1
2	2-5	0	0	0,1	9	0	9	0	0,1	9	0	9	0	0,2	1
3	5-7	0	0	0	9	0	0	0	0	9,1	0	0,1	0	0,2	1
4	24	0	0	0,1	0	0,15	0	0,15	0,1	9	0	0	0	0,5]
5	7-8	0,5	0.5	0	0	0	0.5	0	0	0,1	0	0,1	0,5	mai]
4	34	0,5	0.5	0	0.5	0,15	0.5	0,15	0	0	0	9	0	-]
7	5-6	0,5	63	0	9	0	0,5	0	0	0	0,5	9	0	mini]

Figure 6. Modi®ed optimization procedure for the sample example.

and Linares 1994) is used in combination with the minimal transfer method to build the dispersions data matrix for the simultaneous veri®cation and optimization procedure. However, since no reference values are used, each dispersion participating in the tolerance chain for the design and manufacturing dimensions is given the letter x as a value. Others are given the value zero in the starting data matrix as highlighted by the ®rst table of ®gure 6. Then, we compute the distribution coef®cient k for each design dimension BE using equation (5). The increasing values of this coef®cient give the processing order for the tolerance distribution. It is noticed that for the ®rst iteration k equals the BE tolerance value. Following this order, each line is processed by distributing the design tolerance value among the participating dispersions and their values are saved in the distribution matrix, as explained in ®gure 6 for the example of ®gure 2. In opposition to the minimal dispersions method, where a complete distribution of the residuals is not guaranteed, the unknown dispersions method always distributes the full tolerance values among the unknown dispersions.

$$k_j < \frac{IT_{CBE} \ddot{y}_i^m Dli}{p};$$
 -5f

where

 IT_{CBE} is the tolerance interval for design dimension (BE),

m is the number of known dispersions, p is the number of unknown dispersions, i is the iteration order.

j is the iteration order.

2.4. Procedure for computing manufacturing dimensions

In the veri®cation procedure of the design dimensions, and when the condition of minimum transfer is satis®ed, the manufacturing dimensions participating in the design dimensions are those bounded by surfaces having the two dispersions stationed on the same stage. Thus, we obtain all the manufacturing dimensions in the pre-project. Based on the fundamental model developed by Bourdet (1975) and on the matrix of the pre-project, we can calculate an average length l_i limited by two Dl_i. For each phase, the origin of basic average lengths is taken on the leftmost surface (surface 1, $I_1 = 0$). Using the design dimensions (BE) and the manufacturing dimensions (BM) we build a system of equations to determine the basic average lengths I_i using relations (6) and (7) as follows:

$$Cf_{i\ddot{y}j ave:} < I_j \ddot{y} I_i;$$
 -6f

$$Cpm_{i\ddot{y}j ave:} < I_j \ddot{y} I_i;$$
 -7f

where

Cf_{i-j ave.} is the average design dimension (BE),

 $\mathsf{Cpm}_{i\cdot j}$ $_{ave.}$ is the average minimal stock removal (BM).

Figure 7 explains this procedure for the example of \circledast gure 2. This \circledast gure highlights the system of 12 linear algebraic equations obtained using the data of the preproject. After the solution of the system of equations, the computed values of the average lengths I_i for the eight surfaces are used to calculate the average manufacturing dimensions $CF_{i\cdot j}$ ave. The tolerance interval IT is then computed for each dimension $CF_{i\cdot j}$ using the previously optimized dispersions DI_i on each surface i delimiting the dimension. Figure 7 shows that

For each element ΔE , we correspond a basic average length l_1 . That is : l_1 , l_2 , l_3 , l_4 , l_5 , l_4 , l_5 and l_6 . There are 12 basic average lengths. So $q = 12$ (number of unknowns). We need 12 equations, as follows : $l_4 = 0$ (origin) $l_4 = 0$ (origin) $l_5 = \Gamma_3 = 1^{-1} + 1^{-1}$; We have 7 design dimensions BE and BM, so $p = 7 + 5 = 12$ ($p = q$) Equation given by dimensions BE and BM are : Equation $n^{*1} : (1-2) \cdot l_3 = 16$ Equation $n^{*1} : (1-2) \cdot l_5 - l_6 = 35$ Equation $n^{*1} : (2-5) \cdot l_5 - l_5 = 25$ Equation $n^{*1} : (2-4) \cdot l_5 - l_5 = 15$ Equation $n^{*1} : (2-4) \cdot l_5 - l_5 = 15$ Equation $n^{*1} : (2-4) \cdot l_5 - l_5 = 15$											
Equation n°7 : (5-6) I ₆ - I ₅ = 1,20											
We construct a system of linear equations. After system solution, we have :											
And special services, we have :											
1_1 $1'_1$ 1_2 0 0 16	13 14 29.9 31.25	1 <u>s 1's</u> 51 51	34 34	3 <u>1</u> 6 1 32,2	26 92,15						
Computation of average values for the manufactured dimensions CF :											
li - h h = h	b=h	h=4	4+4	15 - Li	4 - 1						
54 35	25	19,75	92,15	29,9	52,2						
Computation of tolerances for manufacturing dimensions CF : elassical optimization IT CF ₁₄ = ΔI^{μ} (egs. + ΔI_{μ} eqs. = 0.725 + 0.275 = 1 IT CF ₂₄ = ΔI^{μ} spt. + ΔI_{μ} eqs. = 0.09 + 0.11 = 0.2 IT CF ₂₄ = ΔI^{μ} spt. + ΔI_{μ} eqs. = 0.08 + 0.12 = 0.2 IT CF ₂₄ = ΔI^{μ} spt. + ΔI_{μ} eqs. = 0.14 + 0.16 = 0.3 IT CF ₁₄ = ΔI_{μ} eqs. + ΔI_{μ} eqs. = 0.5 + 0.6 = 1.1 IT CF ₁₄ = ΔI_{μ} eqs. + ΔI_{μ} eqs. = 0.5 + 0.5 = 1 IT CF ₁₄ = ΔI_{μ} eqs. + ΔI_{μ} eqs. = 0.5 + 0.5 = 1 Final values for manufacturing dimensions CF :											
CF1.5 CF32	CF ₅₂	CFsd	CV14	CF13	CF14						
512.43 351.43	25(4)	19,75+ 6.15	92,154 6,55	29,91.65	\$2,2+13						
$ \begin{array}{l} Computation of tolerances for manufacturing dimensions CF : modified optimization \\ \Pi^- CF_{1,0} = \Delta \Gamma^- sopt. + \Delta logt. = 0,5 + 0,5 = 1 \\ \Pi^- CF_{3,0} = \Delta \Gamma^- sopt. + \Delta logt. = 0,1 + 0,1 = 0,2 \\ \Pi^- CF_{3,0} = \Delta \Gamma^- sopt. + \Delta logt. = 0,15 + 0,15 = 0,3 \\ \Pi^- CF_{3,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,15 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. + \Delta logt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l_sopt. = 0,5 + 0,5 = -1 \\ \Pi^- CF_{1,4} = \Delta l$											
CF1.5 CF3.2	CF4.7	CFM	CF14	CF13	CF14						

Figure 7. Computation of manufacturing dimensions for the sample example.

SIMULATION OF EXAMPLE OF FIGURE 2 : Number of Phases : 5 Number of Surfaces Number of dimensions BE and BM : 8 0.00 0.00 0.00 0.00 0.03 0.00 0.07 0.00 : 7 The matrix after elimination of lines having one element: 0.00 0.00 0.00 0.00 0.03 0.00 0.07 0.00 Dimensions of BE and EM The matrix after elimination of columns having one N^{*} Roots S. Target S. IT Bil(1/0) Min.D Max.D 1.20 15.40 34.90 16.60 35.10 1 2 0.20 0.20 24.90 15.00 25.10 5 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.50 4 4 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 9 0.00 0 15.00 0.00 0.20 0.00 ó 5 0.00 3 4 ŝ ò 0.20 0.00 4 0.00 The matrix after elimination of lines having one element: VERIFICATION OF THE PRE-PROJECT Computation of $\Sigma \Delta li$ of design dimension 1 between surfaces 1= 1 and m= 2 : The matrix after elimination of columns having one 0.00 0.00 0.00 0.00 0.03 0.00 0.07 0.00 Sum[3]=0.10 IT[3]=0.20 Residual[3]=0.10 Pre-project is verified for design dimension 3 Computation of $\Sigma\Delta$ li of design dimension 4 between surfaces 1= 2 and m= 4 : The matrix after elimination of columns having one The matrix after elimination of lines having one element except 1 and m : element: 0.00 0.05 0.00 0.00 0.03 0.00 0.00 0.00 Sonne[1]=0.63 IT[1]=1.20 Residual[1]=0.57 The matrix after elimination of lines having one Pre-project is verified for design dimension 1 Computation of $\Sigma \Delta li$ of design dimension 2 between surfaces 1= 2 and m= 5 ; The matrix after elimination of columns having one The matrix after elimination of columns having one 0.00 0.05 0.00 0.00 0.03 0.00 0.00 0.00 The matrix after elimination of lines having one 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 element: 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 The matrix after elimination of lines having one element:
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 <td 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 The matrix after elimination of columns having one Sum[4]=0.16 IT[4]=0.50 Residual[4]=0.34 Pre-project is verified for design dimension 4 0.00 0.05 0.00 0.00 0.03 0.00 0.00 Computation of $\Sigma\Lambda li$ of design dimension 5 between surfaces l= 7 and m= 8 : 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 The matrix after elimination of columns having one The matrix after elimination of lines having one element except 1 and m : element: 0.50 0.00 0.00 0.00 0.00 0.00 0.00 0.50 0.00 0.00 0.00 0.00 0.03 0.00 0.07 0.00 Sum[2]=0.08 17[2]=0.20 Residual[2]=0.12 The matrix after elimination of lines having one Pre-project is verified for design dimension 2 Computation of $\Sigma \Delta li$ of design dimension 3 between surfaces l = 5 and m = 7: The matrix after elimination of columns having one 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.03 0.00 0.07 0.00 element except 1 and m :

(continued opposite)

Sum (5) = 1.65 ΣΔ11 ---------- 0.000 Residual of the dimension ---->= 0.120 Number of dispersions to be optimized for the dimension------2 2 Computation of $\sum \Delta 1$ of design dimension 6 between surfaces 1= 3 and m= 4 : The matrix after elimination of columns having one dimension-----Distribution of the residual ->- 0.060 IT of the dimension----->= 0.200 ΣΔ11 ---->= 0.200 Residual of the dimension ---->= 0.000 The matrix after elimination of lines having one element: Bank : 3 Before optimization of dispersions for dimension 4 0.00 0.00 0.11 0.00 0.05 0.00 0.03 0.09 0.00 0.00 0.00 0.00 IT of the dimension---->= 0.500 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 Eali 0.280 Residual of the dimension ---->= 0.220 Sum [6] = 1.63 Computation of $\Sigma \Delta li$ of design dimension 7 between surfaces 1- 5 and m- 6 : The matrix after elimination of columns having one After optimization of dispersions for dimension (0.00 0.00 0.11 0.00 0.16 0.00 0.14 0.09 0.00 0.00 IT of the dimension----># 0,500 ΣA11 ---->= 0.500 Residual of the dimension ---->= 0.000 Rank : 4 The matrix after elimination of lines having one Before optimization of dispersions for dimension 1 0.00 0.59 0.11 0.00 0.00 0.05 0.00 0.09 0.00 0.00 0.00 0.00 IT of the dimension---->= 1.200 ΣΔ11 ---->= 0.750 Recidual of the dimension ---->= 0.450 Number of dispersions to be optimized for the dimension ---->= 2 Sun [7] = 1.55 Distribution of the residual->= 0.225 OPTIMIZATION AND DISTRIBUTION DATA MATRIX FOR DISFERSIONS After optimization of dispersions for dimension 1 0.00 0.72 0.11 0.00 0.00 0.27 0.00 0.09 0.00 0.00 0.00 0.00 IT of the dimension---->= 1.200 ΣΔ11 ---->= 1.200 Residual of the dimension ---->= 0.000 Optimized dispersions 0.500 0.725 0.110 0.500 0.160 0.275 0.140 0.090 OPTIMIZATION OF DISPERSIONS 0.080 0.500 0.120 0.500 S(1)=0.630 IT(1)=1.200 Residual(1)=0.570 S(2)=0.080 IT(2)=0.200 Residual(2)=0.120 S(3)=0.100 IT(3)=0.200 Residual(3)=0.100 COMPUTATION OF THE MANUFACTURING DIMENSIONS S[4]-0.160 IT[4]=0.500 Residual[4]=0.340 Equation[1]: Equation[2]: 0.000 - L 1 16.000 = L 2 - L 1 35.000 = L 5 - L 2 25.000 = L 7 - L 5 Equation[3]: Residual Processing order Rank Equation[4]: 0.100 15.250 = L 4 - L 2 Equation[5]: 2 0.120 . Equation[6]: 16.100 = L 8 - L 7 0.340 4 Equation[7] 1.350 - 1.4 0.570 Equation[8]: 1.200 = L 6 - L -5 Rank : 1 System of equations: Before optimization of dispersions for dimension 3 1L1+0L2+0L3+014+0L5+0L6+0L7+0L8 = 0.000 -11.1+11.2+01.3+01.4+01.5+01.6+01.7+01.8-16.000 011-11.2+01.3+01.4+11.5+01.6+01.7+01.8=35.000 IT of the dimension----->= 0.200 ΣΔ11----->= 0.100 Residual of the dimension ---->= 0.100 011+012+013+014-115+016+117+018 =25.000 0L1-1L2+0L3+1L4+0L5+0L6+0L7+0L8 =15,250 0L1+0L2+0L3+0L4+0L5+0L6-1L7+1L8 =16,100 0L1+0L2-1L3+1L4+0L5+0L6+0L7+0L8 = 1.350 Distribution of the residual ->= 0.050 0L1+0L2+0L3+014-1L5+1L6+0L7+0L8 = 1.200 After optimization of dispersions for dimension 3 Manufacturing dimensions Solution L 0.000 L[1]= 0.000 L[2]= 16.000 CF(1 5]=51.00 10.50 IT of the dimension----->= 0.200 £. 3]= 29.900 4]= 31.250 CF[2 5]=35.00 ±0.10 ΣΔ11 ----->= 0.200 Residual of the dimension ---->= 0.000 CF[5 7]=25.00 ±0.10 L(5)= 51.000 L(6)= 52.200 CF[4 5]=19.75 ±0.15 Rank 1 2 CF[1 8]=92.10 10.50 1.0 71- 76.000 Lf R1= 92,100 CF[1 3]=29.90 ±0.50 CF[1 6]=52.20 ±0.50 0.00 0.00 17 of the dimension---->= 0.200

Figure 8. Results of the automated simulation for the sample example.

the @nal tolerance values given by the modi@ed dispersions optimization method for the simple example are similar to the results given by the classical dispersions optimization method. However, in reality, the former always gives better results than the latter, as was veri@ed with more complex examples. Furthermore, the modi®ed dispersions method overcomes the problem of unknown minimal reference dispersions that are not always available in the industrial literature or are dif@cult to assess from experience.

3. Programming and validation tests for the simulation

The procedures forming the simulation have been integrated in one module and programmed in order to be tested. The @nal computer program consists of @ve functions. The ®rst function permits the input and preparation of the pre-project data in matrix format. The second function performs the pre-project veri®cation and eventual solution of impossible tolerance transfer. The third function executes the optimization procedure of dispersions. The fourth function computes the manufacturing dimensions. The ®fth function computes the setting dimensions. The program is validated by practical and complex process plan simulations and is compared to classical manual simulations (Hamou 1998). Figure 8 gives an overview of the output results of the developed module for the pre-project sample of @gure 2. This software, which is designed as a standalone module, can be easily integrated in a CAPP system or a more general CAD/ CAM system. The program can extract its initial preproject data from the upstream CAPP modules. On the other side, it can communicate its simulation results to the downstream departments of manufacturing, such as numerical control processing activities.

4. Conclusions and perspectives

The objectives set forth by this research work were to automate the process plan simulation activity as a separate module or within a CAPP system. The manufacturing dispersions or capabilities are at the root of the development of a combined programmable methodology, based on the minimal transfer method, the minimal reference dispersions method and a proposed modi®ed dispersions method. It is shown that the modi®ed dispersions method performs a simultaneous veri®cation and optimization without the need of the minimal reference dispersions that are not always available for all processes. On the basis of the developed programmed methodology, a computerised module has been designed in the form of three procedures. The ®rst procedure permits the veri®cation of the process plan pre-project. The second procedure permits an optimization of dispersions. The third procedure permits the computation of the optimized manufacturing dimensions and tolerances. The ®nal module of simulation has been tested on complex examples. These results have shown that the methodologies used can help process designers in the activity of manufacturing tolerance analysis and distribution within a CAPP system. Further research is undergone on one side, in order to perform a nonequal redistribution of excess tolerance depending on the complexity of the manufacturing dimensions. On the other side, investigations are being conducted for automating the extraction of a manufacturing tolerance chain in order to perform a cost-based statistical optimization of tolerance transfers and distribution on the manufacturing dimensions.

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