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# Online sonification for golf putting gesture: Reduced variability of motor behaviour and perceptual judgement

Benjamin O'Brien, Brett Juhas, Marta Bieńkiewicz, Frank Buloup, Lionel Bringoux, Christophe Bourdin

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**Abstract** This study investigates whether real-time auditory feedback has a direct behavioural or perceptual effect on novices performing a golf putting task with limited visual feedback. Due to its significant role in the success of a putt, club head speed was selected as the parameter for sonification. Different combinations of synthesisers, timbral modulations, scales, and mappings were developed to examine whether particular sound classes influenced performance. When compared to trials with static pink noise, we found that, despite their vision being limited at impact, participants were able to use different types of sonification to significantly reduce variability in their distance from the target and ball location estimation. These results suggest concurrent sound can play an important role in reducing variability in behavioural performance and related perceptual estimations. In addition, we found that, when compared to trials with static pink noise, participants were able to use sonification to significantly lower their average impact velocity. In the discussion we offer some trends and observations relative to the different sound synthesis parameters and their effects on behavioural and perceptual performance.

Keywords sonification, auditory feedback, kinematics, motor coordination, golf

#### 1 1 Introduction

<sup>2</sup> A recent research trend has focused on studying the effects of online auditory feedback on

<sup>3</sup> human movement. [44] found that participants were able to perceive and associate move-

<sup>4</sup> ment profiles when acoustic information was concurrent with their movement. Speed and

<sup>5</sup> fluency were improved in novel handwriting tasks when kinematic movement was mapped

6 to sound [10]. [12] demonstrated that online auditory feedback can enhance complex motor

7 learning and make tracing bimanual shapes more easily repeatable. There is increasing ev-

<sup>8</sup> idence that online *sonification*, the real-time use of sound to represent data, is an effective

<sup>9</sup> medium for conveying motor-related information.

Its effectiveness may be because auditory cues are more temporally accurate than visual ones [22, 31]. In comparison, auditory information seems less demanding of attention and

<sup>12</sup> more portable [41]. A summary of psychophysical research also suggests sound can prompt

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dynamic cues that are beyond the field of vision [16,32]. This point is underscored by a
significant sonification of movement study by [39], which found brain activity increased
in the human action observation system when participants viewed congruent audiovisual
movement as opposed to incongruent movement. These studies suggest why augmenting
auditory, as opposed to visual, information might be more suitable for channelling supple-

mental information.
 Research suggests that the repetition of auditory-motor activities promotes neural cou-

<sup>20</sup> pling [38,21], which, through entrainment, can make these actions more easily repeatable.

[9] showed that listening to auditory rhythmic stimuli primed participants while they com-

<sup>22</sup> pleted tasks tapping to auditory stimuli. Similar evidence of interactions between the au-

ditory and motor systems was shown in studies by [43,28,29], which showed participants

<sup>24</sup> used rhythmic auditory cues as references to predict, prepare, and anticipate movements.

There are numerous studies that have examined the differences in motor cortex activity between skilled musicians, who carefully manipulate their hands with instruments, and non-

<sup>26</sup> between skilled music<sup>27</sup> musicians [2, 30, 40].

Like musicians, athletes also require a high-level of fine motor control that is easily re-28 peatable. [7] showed that elite swimmers enhanced their motor control by using real-time 29 sonification based on pressure exerted by their hands. [1] found gymnasts were able to use 30 concurrent auditory feedback to correct complex movements. These works demonstrate how 31 highly skilled athletes are capable of improving mechanics when training with online sonifi-32 cation. However, there appears to be only a few studies that focus on the effects of real-time 33 auditory feedback on novices. A major study by [14] found that novice rowers, who experi-34 enced online sonification of four movement parameters, were able to increase their average 35 boat velocity. Similarly, we were interested in studying the effects of sound on novices and 36 whether it enhanced their natural execution of a complex motor task. 37 For our study, we selected golf, as it fits the definition of a sport involving a complex 38 motor task [50]. Although the physical fitness required to play and succeed in golf is vast, it 39 requires expert concentration, precision, and force management in order to swing a golf club 40 [5]. In addition, golf requires players to keep their eyes on the ball before making contact, 41 which stresses the importance of other sensory cues for guiding the gesture. These pre-42

requisites make it an ideal candidate for studying whether sound can be used as an effectivetool for novices.

We decided to focus on golf putting, as the sole purpose of using the putter is to get the 45 ball to a specified target by controlling club head motion at impact [8]. The putting motion 46 requires considerable fine motor control processes in order to move the putter at a speed in 47 which impact is adequate enough for the ball to follow the intended path and distance to the 48 target [5]. In general, the gesture can be partitioned into two sub-movements: the backswing 49 and the downswing. While there are many ways to swing the putter, for example, increasing 50 movement in the wrist or elbow, these two phases remain and are required to be effective at 51 getting the ball to the target. Although research has been conducted on identifying an 'ideal 52 ratio' of backswing to downswing, golfers may apply different forces during these phases, 53 but nonetheless have comparable velocity profiles [20,26]. 54

With a population of novice golfers, we anticipated that our participants would have diverse putting swing mechanics and therefore require a robust sonification parameter that could accommodate these differences. Because some participants might choose to putt by fixing their wrists, creating parallel as opposed to angular movement between the hands and the club head, we selected club head linear velocity as the candidate for sonification. [42] reviewed numerous studies that found success in developing artificial auditory feedback

<sup>61</sup> based on velocity. In addition [17] posited that listeners can make ecological observations

<sup>62</sup> based on aerodynamics and mechanical noise and use them as auditory indices. For example,

63 listeners might identify changes in speed by identifying sounds associated with the wind or

<sup>64</sup> a car engine. More recently, [3] found that the movement of novice golfers was influenced

<sup>65</sup> by the presence of auditory guidance based on club head speed. Based on this research, we

<sup>66</sup> believed that if participants could perceive that their movement had a direct and immediate

<sup>67</sup> effect on the sounds they heard, then we might observe changes to their motor behaviour.

As there are innumerable ways to map data-to-sound [19], it was important to develop 68 69 sound that participants could easily perceive and interpret as metaphor for club head speed. Although research has shown that healthy people can extract information from character-70 71 istics in sound [6], such as an object's size [27] or material [49], they do not perceive sound similarly due to their physiological and psychological differences. Based on [25], 72 who found that patterns of individual differences identified in healthy adults similarly af-73 fected their auditory performance, we expected participants would most likely perceive, 74 interpret, and possibly use artificial sounds based on their movement on an individual-basis, 75 if at all. Therefore, as a way of maximising the potential for participants to engage with and 76 become influenced by sound, our goal was to develop and combine methods for mapping 77 club head speed to parameters controlling sound synthesis and study their effects on perfor-78 mance. By doing so, we might develop a method for enhancing performance by sonifying 79 the golf putting gesturing. 80 Although the effect of sound on golf putting can be easily measured by calculating 81 the distance between the target and the final position of the ball, a more elaborate method 82 was required to evaluate whether artificial sound affected their perception. If participants 83

<sup>63</sup> could visually assess the distance between the ball and the target, they would most likely
 <sup>64</sup> make adjustments to their swings, which would make it impossible to measure whether
 <sup>66</sup> visual or auditory factors played significant roles on performance. However, if their vision
 <sup>87</sup> was masked after impact with the ball, participants would be forced to rely on audition to

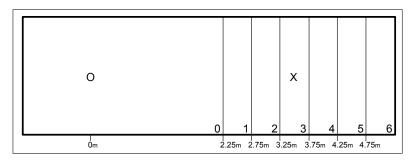
estimate ball distance and assess their performance. In turn, this extra-sensory information
 could be used to influence the performance of future putting attempts.

The primary goal of our study was to examine whether real-time auditory feedback can play a significant role in behavioural performance and its perceptual correlates. Specifically we wanted to study whether online sonification had an immediate effect on performance, as opposed to studying its effects on novices learning a complex motor skill. A corollary then was to examine whether sonification affected aspects required to execute the complex motor task and, if so, were there any correspondences with performance.

#### 96 2 Methods

#### 97 2.1 Participants

<sup>98</sup> Twenty right-handed participants (12 male; ages  $24.2 \pm 6.7$ ) affiliated with Aix-Marseille <sup>99</sup> University participated in the experiment. All participants had good or corrected vision and <sup>100</sup> hearing and self-reported having no motor control problems and being right-handed. All <sup>101</sup> participants consented to voluntary participation in the study and were informed of their <sup>102</sup> right to withdraw at any time. This study was performed in accordance with the ethical <sup>103</sup> standards of the Declaration of Helsinki [37]. The protocol was approved by the Ethics <sup>104</sup> Committee of Aix-Marseille University.



**Fig. 1** Overhead diagram of putting terrain, where **O** is the starting position (0 m) and **X** is the target (3.5 m). Zones 0-6 are 0.5 m apart.

#### <sup>105</sup> 2.2 Experimental setup

#### 106 2.2.1 Materials

Participants used an Odyssey White Ice putter (length: 0.97 m; weight: 0.59 kg) to hit Titleist 107 PRO V1X balls. A synthetic grass terrain was used (length: 5 m; width: 1.8 m). The target 108 was a painted white circle with a 0.11 m diameter, which is the same size as a conventional 109 golf course hole. Beginning 2.25 m away from the starting position, six different coloured 110 lines were painted 0.5 m apart. These lines denoted zones 0-6, where the target was located 111 in zone 3 (Figure 1). A HD Video Camera-Pro Webcam C930e was mounted on the ceiling 112 above the putting terrain and overlooked the putting hole (2.5 m), which was used to measure 113 the accuracy of each putt. All participants wore Sennheiser headphones and shutter glasses 114 throughout the course of the experiment. 115

#### 116 2.2.2 Sound Design

Participants were presented 24 different sonifications, which were created by combining dif-117 ferent synthesisers, timbral modulations, scales, and mappings. Unlike some sounds, such 118 as piano notes, which might carry additional, nested information to some participants in 119 ways that might affect their performance, our method allowed us to parameterise and de-120 velop different sounds that might be more contextually relevant to the performance of the 121 golf putting gesture. Although their development is described in greater detail in [33], the 122 following offers a brief description. 123 Following closely to the action-object paradigm [17], we designed two synthesisers with 124

the goal of getting participants to perceive or imagine the properties of the object (the putter) 125 or the morphologies that carry information about the action (the golf putting gesture). The 126 whoosh synthesiser produced a sound similar to that of a metal object passing through the 127 air by mapping club head speed to the center frequency of a second-order IIR digital res-128 onator filter (decay rate: 30 ms) with white noise input. In order to bring attention to swing 129 speed we wanted to create an exaggerated sound based on the sound of metal-air contact via 130 mechanical processes. Adapting a model developed by [15], our jet synthesiser mapped club 131 head speed to a speed scalar with a range of 0.0 ("engine off") and 1.0 ("engine maximum 132 speed"). This signal was then filtered by a single-pole low-pass filter with a 0.2 Hz center 133 frequency, creating the auditory effect of a mechanical system speeding up or slowing down, 134

which then scaled the frequencies of five sine wave oscillators.

Given the two synthesisers, we wanted to examine whether there were any effects on performance if club head speed was mapped to parameters that modulated either sound *brightness* [48,34] or *rhythmicity*<sup>1</sup>. To study the effects of one parameter, of course the other must remain fixed. Therefore, when velocity was mapped to parameters that modulated brightness, it was not mapped to rhythmicity parameters, and vice-versa.

The scale in which to map club head speed to brightness was different for each syn-141 thesiser. Based on similar selections made in a sonification of golf putting study by [3], we 142 selected a frequency range of 80-1000 Hz for the whoosh, as it is just below the 2-5 kHz 143 sensitivity of the human ear. The jet was composed of five sinusoidal oscillators with dif-144 ferent amplitudes and maximum frequencies (3-11 kHz), which were scaled between 0.0 to 145 1.0 relative club head speed ("speed scalar"). As the human auditory system is sensitive to 146 frequencies from 20 Hz to 20 kHz, both synthesisers produced sounds in the lower half of 147 this frequency sensitivity spectrum. It is commonplace that sensitivity to upper-range fre-148 quencies degrades with age, although this was most likely not a factor for our participants. 149 150 Thus, we selected frequency ranges of 540-1000 Hz (1:1) and 80-1000 Hz (1:2) for the 151 whoosh and 0.5-1.0 (1:1) and 0.0-1.0 (1:2) for the jet. The scale in which to map speed to rhythmicity was similar for both synthesisers, so a single method was developed that con-152 tinually repeated the process of sending attack-decay-release envelopes (attack: 5 ms). For 153 decay times we selected a range between a fifth and a fiftheth of a second, which yielded 20-154 110 ms (1:1) and 20-200 ms (1:2). Unlike the relationship with brightness, speed and decay 155 length are inversely proportional, so that club head speed and impulse rate are proportional. 156 To map club head speed onto sound we required a function. Because sound pressure 157 levels are typically measured logarithmically in dB, we wanted to examine whether any 158 effects on performance if club head speed was mapped logarithmically (base 2). We then 159 wanted to observe if there were any differences in comparison to its inverse - exponential 160 (coefficient 2) - and linear mappings. 161 All sonifications are listed in **Table 1. Appendix 1** illustrates club head speeds per-162

formed by a participant when presented different auditory conditions. The Supplementary
 Materials demonstrate some of the sound synthesis combinations and their effects on sound
 produced from club head speed.

In addition to the 24 different sonifications described above, a static pink noise case was added to serve as a reference, such that its synthesis and display were independent of movement. The static pink noise was to control for the effect of headphones, but not to isolate the participants from the environmental sounds, including ball impact. To demonstrate that the sound of impact was available to participants across the different auditory conditions, **Appendix 2** illustrates a participant performing the golf putting task with and without static pink noise.

#### 173 2.2.3 Task

Participants were tasked with hitting a golf ball towards a 3.5 m target. While completing the putting gesture, participants were exposed to different sonifications (**2.2.2**). Once participants made contact with the ball, their shutters closed. Their second task was then to estimate the final distance of the ball. Participants verbally offered a number that corresponded to a provided diagram that outlined zones on the putting terrain (**Figure 1**). An experimenter then measured the distance between the ball and the target, which was used as a reference

<sup>&</sup>lt;sup>1</sup> Rhythmicity can be described as creating a sense of accelerating or decelerating rhythms by changing the decay times of envelopes applied to a continuous sound.

Synthesiser	Modulation	Scale	Mapping	Number
Whoosh	Brightness	1:1	Linear	1
			Exponential	2
			Logarithmic	3
		1:2	Linear	4
			Exponential	5
			Logarithmic	6
	Rhythmicity	1:1	Linear	7
			Exponential	8
			Logarithmic	9
		1:2	Linear	10
			Exponential	11
			Logarithmic	12
Jet	Brightness	1:1	Linear	13
			Exponential	14
			Logarithmic	15
		1:2	Linear	16
			Exponential	17
			Logarithmic	18
	Rhythmicity	1:1	Linear	19
			Exponential	20
			Logarithmic	21
		1:2	Linear	22
			Exponential	23
			Logarithmic	24

 Table 1
 Sonification types

to compare against the webcam recordings (2.2.4), removed the ball, and then reopened the

181 participant's shutters.

<sup>182</sup> After completing a sequence of 25 experimental trials, whose order was pseudo-randomised,

<sup>183</sup> participants had five calibration trials to avoid a drift of overshooting the target due to the

<sup>184</sup> lack of visual assessment during the experimental trials. During these trials, shutters re-

mained opened and participants were presented static pink noise. 25 experimental trials

followed by 5 calibrations were repeated five times for a total of 145 putts, where the last 5

187 calibrations were removed from testing.

#### 188 2.2.4 Data recordings and statistics

189 Codamotion CX1 Scanner was used to measure club head and hand grip position data (dis-

tance: 2 m; elevation: 1 m; sampling rate: 200 Hz). Two infra-red active markers were placed
 near the club head at the bottom of the club shaft and below the hand grip. Each marker po sition was encoded into an 8-byte message that was sent locally to a separate computer

running Max/MSP for sound synthesis.

A custom Max/MSP program was used to decode each 2-byte club head position vector value, which was used to calculate club head linear velocity  $v_t$  at time *t* and marker values  $x_t$  and  $z_t$  (1). In addition, Max/MSP was used to capture images with the webcam (sampling rate: 0.2 Hz).

$$v_t = \sqrt{\left(\frac{x_t - x_{t-1}}{t_t - t_{t-1}}\right)^2 + \left(\frac{z_t - z_{t-1}}{t_t - t_{t-1}}\right)^2} \tag{1}$$

Because our goal was to examine the effects of online sonification, it was important to minimise latency between club head speed and the sound synthesised from it. While we were unable to calculate temporal differences in auditory processing between participants, it was important to determine a latency reference that was not so large that it might inad-

vertently affect performance. A pretest was developed, where sound would be generated by

<sup>203</sup> a sinusoidal oscillator (frequency: 200 Hz) if the CodaMotion marker located near the club

<sup>204</sup> head crossed a pre-determined point under a ball. A microphone was placed near the ball to

<sup>205</sup> record the sound of impact, while the sound generated by Max/MSP was stored directly on a

206 computer. Three novice participants were instructed to perform 20 3.5 m putts. Empirically

207 comparing the start times of the sound of impact and the sound generated in Max/MSP, we

determined a 25-28 ms delay. For the three participants, the average putting duration was  $1.05 \pm 0.22$ 

 $1.05 \pm 0.32$  seconds, and we decided a latency of around 2.3-2.6% was not meaningful.

To examine the effects of real-time auditory feedback on behavioural performance and 210 perceptual correlates, two variables were used. To assess the success of a putt, we measured 211 212 the distance between the target and the final position of the ball, or the target distance error (TDE). Using a similar method described in [3], we selected the image with the final po-213 sition of the ball and calculated the distance between target and the ball by using a custom 214 MATLAB program. This calculation was then compared to our manual distance calculation, 215 where any discrepancies were averaged but did not exceed 1 cm. To quantify perceptual ac-216 curacy and precision, we calculated the difference between the estimation and the observed 217 final ball position, or the zone estimation error (ZEE). Because we were interested in both 218 participant average and variability, for both *TDE* and *ZEE* we calculated both the mean  $(\mu)$ 219 and standard deviation ( $\sigma$ ). 220

To better understand the relationship between putting performance and swing mechanics and the potential influence of sound on them, we analysed impact velocity (*IV*). [8] reported a strong direct correlation between putting distance and velocity at impact, ranging from 0.98 to 0.99. These findings support observations made by [5], which underscore the importance of club head speed in order to have successful putts. Thus, we wanted to examine whether real-time auditory feedback might affect impact velocity in manner similar to performance. Both impact velocity average  $IV_{\mu}$  and standard deviation  $IV_{\sigma}$  were calculated.

In our preliminary analysis, we wanted to first confirm group normality and analysed all participant  $TDE_{\mu}$  and  $ZEE_{\mu}$  during experimental trials by calculating their respective zscores. All participants were included in our study,  $|z| < 3\sigma$ . Next, we wanted to confirm our method of sound randomisation did not bias any one sound and, by applying Repeated Measures ANOVAs, found no main effect of sound position in sequence on  $TDE_{\mu}$  nor  $TDE_{\sigma}$ , p > 0.05. Thus, all sounds were treated as equal and independent of their position in the experimental trial sequence.

For all outcome variables, Repeated Measures ANOVAs were carried out with Greenhouse-Geisser adjustments. We reported main effects on synthesiser (*whoosh, jet*) and modulation (brightness, rhythmicity). Because club head speed was mapped to a selected mapping function (linear, exponential, logarithmic) onto a scale (1:1, 1:2), which was different depending on the type of synthesiser selected, we decided to also report interactions between synthesiser \* scale \* mapping. Where main effects and interactions were detected, post-hoc Bonferroni-adjusted t-tests were carried out with the alpha level set to 0.01.

#### 242 3 Results

#### 243 3.1 Target Distance Error

To examine whether real-time auditory feedback influenced putting performance, we anal-244 ysed both  $TDE_{\mu}$  and  $TDE_{\sigma}$ . For the  $TDE_{\mu}$ , we found main effects for types of synthesiser 245  $F_{2,38} = 27.24, p < 0.001, \eta_p^2 = 0.59$  and modulation  $F_{2,38} = 27.63, p < 0.001, \eta_p^2 = 0.59$ , and 246 an interaction between synthesiser \* scale \* mapping  $F_{4,76} = 35.44$ , p < 0.001,  $\eta_p^2 = 0.65$ . 247 But post-hoc tests revealed no significant differences when comparing trials associated with different sound synthesis parameters to those with static pink noise, p > 0.05. For  $TDE_{\sigma}$ , we 249 found main effects for types of synthesiser  $F_{2,38}$  = 41.2, p < 0.001,  $\eta_p^2$  = 0.68, modulation 250  $F_{2,38} = 41.35, p < 0.001, \eta_p^2 = 0.69$ , and an interaction between synthesiser \* scale \* map-251 ping  $F_{4.76} = 51.75$ , p < 0.001,  $\eta_p^2 = 0.73$ . Post-hoc tests revealed the following had lower 252 target distance error standard deviation averages when compared to those associated with the 253 static pink noise trials: synthesisers whoosh (7.98  $\pm$  1.69), p < 0.001, and jet (6.87  $\pm$  1.72), 254 p < 0.01; modulations brightness (7.43 ± 1.76), p < 0.01, and rhythmicity (7.43 ± 1.64), 255 p < 0.001; an interaction between the jet and 1:1 \* exponential mapping (10.34  $\pm$  1.84) 256 and 1:2 \* linear mapping (7.35  $\pm$  1.42), p < 0.01; and an interaction between the whoosh 257 \* 1:1 and linear mapping (10.55  $\pm$  2.31), exponential mapping(8.18  $\pm$  2.11), logarithmic 258 mapping (8.1  $\pm$  1.77), p < 0.001. Figures 2a-b illustrate the differences between  $TDE_{\mu}$ 259 and  $TDE_{\sigma}$  when comparing different synthesisers and static pink noise trials. These results 260 suggest that when real-time auditory feedback was present, participants did not significantly 261

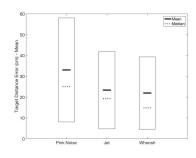
reduce their average ball distance to the target, but were able to reduce their variability.

#### 263 3.2 Zone Estimation Error

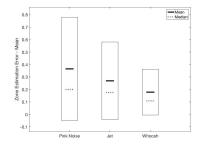
To examine whether real-time auditory feedback had an effect on ball distance estimation, 264 we analysed both  $ZEE_{\mu}$  and  $ZEE_{\sigma}$ . For  $ZEE_{\mu}$ , we found main effects for types of synthe-265 siser  $F_{2,38} = 11.59$ , p < 0.001,  $\eta_p^2 = 0.38$ , modulation  $F_{2,38} = 12.84$ , p < 0.001,  $\eta_p^2 = 0.4$ , and 266 an interaction between synthesiser \* scale \* mapping  $F_{4.76} = 15.28$ , p < 0.001,  $\eta_p^2 = 0.45$ . 267 But post-hoc tests revealed no significant differences when comparing trials associated with 268 different sound synthesis parameters to those with static pink noise, p > 0.05. For  $ZEE_{\sigma}$ 269 there were main effects for types of synthesiser  $F_{2,38} = 31.89$ , p < 0.001,  $\eta_p^2 = 0.63$ , modu-270 lation  $F_{2,38} = 33.34$ , p < 0.001,  $\eta_p^2 = 0.64$ , and an interaction between synthesiser \* scale \* 271 mapping  $F_{2,38} = 31.37$ , p < 0.001,  $\eta_p^2 = 0.62$ . However, the post-hoc tests revealed that only 272 the whoosh synthesiser had a significantly lower average standard deviation when compared 273 to both static pink noise  $(0.26 \pm 0.1)$  and jet  $(0.13 \pm 0.05)$  trials, p < 0.05. Figures 2c-d 274 illustrate the differences between  $ZEE_{\mu}$  and  $ZEE_{\sigma}$  when comparing different synthesiser 275 and static pink noise trials. These results suggest that the presence of real-time auditory 276 feedback did not have a significant effect on estimating ball distance, however, when some 277 synthesis parameters were used, it did play a role in reducing estimation variability. 278

#### 279 3.3 Impact Velocity

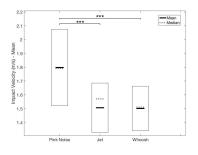
To examine whether real-time auditory feedback played a similar role in both performance and swing mechanics, we analysed impact velocity ( $IV_{\mu}$  and  $IV_{\sigma}$ ). For  $IV_{\mu}$  there were main



(a)  $TDE_{\mu}$  - synthesisers & static pink noise trials

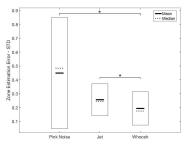


(c)  $ZEE_{\mu}$  - synthesisers & static pink noise trials

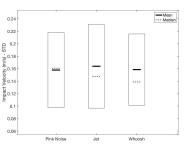


(e)  $IV_{\mu}$  - synthesisers & static pink noise trials

(b)  $TDE_{\sigma}$  - synthesisers & static pink noise trials



(d)  $ZEE_{\sigma}$  - synthesisers & static pink noise trials



(f)  $IV_{\sigma}$  - synthesisers & static pink noise trials

**Fig. 2** Comparisons between Target Distance Error mean  $(TDE_{\mu})$  (a) and standard deviation  $(TDE_{\sigma})$  (b), Zone Estimation Error mean  $(ZEE_{\mu})$  (c) and standard deviation  $(ZEE_{\sigma})$  (d), and Impact Velocity mean  $(IV_{\mu})$ (e) and standard deviation  $(IV_{\sigma})$  (f) for synthesisers and static pink noise trials. {\*, \*\*, \*\*\*} mark significance for  $p < \{0.05, 0.01, 0.001\}$ . Boxes represent the standard deviation from mean.

282 effects for types of synthesiser  $F_{2,38} = 1468.77$ , p < 0.001,  $\eta_p^2 = 0.99$ , modulation  $F_{2,38} =$ 

<sup>283</sup> 1471.25, p < 0.001,  $\eta_p^2 = 0.99$ , and an interaction between synthesiser \* scale \* mapping <sup>284</sup>  $F_{2,38} = 1450.28$ , p < 0.001,  $\eta_p^2 = 0.99$ . Post-hoc tests revealed both types of synthesisers <sup>285</sup> and modulations had significantly lower impact velocity means when compared to those as-<sup>286</sup> sociated with the static pink noise trials: whoosh (0.3 ± 0.05), jet (0.29 ± 0.04), brightness

 $(0.29 \pm 0.04)$ , and rhythmicity  $(0.29 \pm 0.05)$ , p < 0.001. Similarly, we found all interac-

tions (n = 12) between synthesiser \* scale \* mapping had significantly lower impact velocity

means when compared to those associated with the static pink noise trials, where the average 289 difference between them was  $\mu_n = 0.29 \pm 0.03$  and the average standard error was  $\mu_n = 0.05$ 290  $\pm$  0.01, p < 0.001. For  $IV_{\sigma}$  there were main effects for types of synthesiser  $F_{2,38} = 121.01$ , 291 p < 0.001,  $\eta_p^2 = 0.86$ , modulation  $F_{2,38} = 118.8$ , p < 0.001,  $\eta_p^2 = 0.86$ , and an interaction 292 between synthesiser \* scale \* mapping  $F_{4,76}$  = 113.46, p < 0.001,  $\eta_p^2 = 0.88$ . But post-293 hoc tests revealed no significant differences when comparing trials associated with different 294 sound synthesis parameters to those with static pink noise, p > 0.05 Figures 2e-f illustrate 295 the differences between  $IV_{\mu}$  and  $IV_{\sigma}$  when comparing different synthesiser and static pink 296 noise trials. These results reveal sound played a significant role in affecting average impact 297 velocity, but not its variability. 298

#### 299 4 Discussion

Our goal was to examine whether real-time auditory feedback played a role in the be-300 havioural or perceptual performance of novice golfers when vision was limited and study 301 any similarities. With regards to the effect of sonification on average target distance error, 302 we reported significant main effects and interactions, but our post-hoc results revealed no 303 significance. However, both synthesisers and modulations had lower average target distance 304 error when compared to trials with static pink noise: whoosh (11.1  $\pm$  4.88), p = 0.08; jet 305  $(9.68 \pm 4.67)$ , p = 0.13; brightness  $(10.26 \pm 4.65)$ , p = 0.09; and rhythmicity  $(10.51 \pm 10.00)$ 306 4.89), p = 0.1. Despite trials associated with each synthesiser and modulation having lower 307 target distance error averages of approximately 10 cm when compared to those with static 308 pink noise, neither was found to be significant. 309

In comparison to trials associated with static pink noise, we observed that participants 310 were able to significantly reduce their target distance error standard deviation when pre-311 sented either type of synthesiser or modulation. This suggests they were able to interpret 312 information regarding their speed and make adjustments to their motor control in ways that 313 stabilised their ball distance from the target performance. This important result supports ev-314 idence that the auditory channel is well-suited to act as a conduit for which motor-related 315 information can be transmitted [42, 10, 4, 1]. Our results build upon those reported in [47], 316 where concurrent sound was shown to improve performance by reducing temporal irregu-317 larities, as we found novices completing a more complex motor task were able to use sound 318 to reduce performance variability. 319

While the important take away is that participants improved their target distance error 320 standard deviation when presented sonification, no synthesiser or modulation class distin-321 guished itself from another. Interestingly, we found that when participants were presented 322 sonification based on the combination of the whoosh \* 1:1 scale plus any mapping type, 323 they were able to significantly reduce their target distance error standard deviation when 324 compared to static pink noise. It is possible participants found it easier to use sounds gen-325 erated by the whoosh synthesiser when club head speed was mapped onto a more limited 326 scale. Based on the findings made in [25], we anticipated that participants would perceive 327 and interpret the 24 different types of sonification differently, which, in turn, might affect 328 performance. As demonstrated in the Supplementary Materials the timbral differences 329 between synthesisers and modulations are considerable, while the scales and mapping func-330 tions are purposefully more abstract and, depending on their combination, possibly less ob-331 vious to listeners. Despite our care and interest in developing distinguishable sounds based 332 on a complex motor task, there are still many questions regarding the effects of sound on 333

334 human movement.

Our zone estimation error standard deviation results showed that only the whoosh syn-335 thesiser proved to be significantly different from both static pink noise and jet, whereas 336 no other synthesis parameter affected performance. Interestingly, this synthesiser produced 337 sounds with a more limited frequency spectrum, and it is possible that participants found 338 them easier to interpret and read their movements as embedded in the sound [25][23]. [3] de-339 veloped a similar synthesiser for their golf putting study, which reported novice participants 340 exposed to sound improved motor learning. These studies together provide further evidence 341 that, when studying the relationship between human audition and motor control, an ecolog-342 ical, as opposed to timbrally rich or complex, sound might be more affective [17]. Reports 343 and findings from [42, 11, 13] similarly advocate the use of more ecological sounds as a way 344 of maximising sonification efficiency while executing motor tasks. By coupling these find-345 ings with our target distance error standard deviation results, sonification can clearly be used 346 by novices to improve performance variability, however, its significance appears to depend 347 on sound type and the goal of its use. 348

Interestingly, participants did not improve their average zone estimation error when pre-349 sented real-time auditory feedback. Although we observed a trend towards an effect on target 350 distance error average, our post-hoc tests offered little evidence of this when considering av-351 erage zone estimation error. This result differs from those reported in a pilot study by [33], 352 where participants were able to identify swing speed as represented by auditory signals, 353 and [31], which found expert golfers were able to recognise their own idiosyncratic swings 354 via sonification. Unrelated to golf, [45] similarly found participants were able to associate 355 profiles with particular shapes. However, it is possible that our task was much too difficult 356 and complex for the participants to adequately complete, as they were asked to estimate the 357 distance of an object (ball) that was displaced by another (putter) as a consequence of their 358 speed. This of course requires participants to make predictions based on their interpretation 359 of 24 different sounds acting as metaphors for their speed. 360

In general, it appears sonification affected both target distance error and zone estimation 361 similarly. While sonification did not appear to significantly influence average performance, 362 it did similarly affect the variability of motor and, when presented the whoosh synthesiser, 363 perceptive aspects of the task. Using a linear regression model, we computed the correlation 364 between the two variables for each participant during the trials with the whoosh synthesiser 365  $(R^2 = 0.51, p < 0.001)$  and static pink noise  $(R^2 = 0.28, p < 0.05)$ . Figures 3a-b illustrate 366 and compare the models. The significant relationship between target distance error and zone 367 estimation error standard deviation when the whoosh synthesiser was present strongly sug-368 gests participants were capable of reading their movement in sound in a way that allowed 369 them to stabilise their putting performance and estimations based on them. Based on these 370 results, we might hypothesise that by presenting novices with online sonification, their re-371 duced performance variability would make them more consistent, which would then allow 372 professional trainers to better instruct on making swing modifications to improve overall 373 performance [46, 18]. 374

We observed that participants were able to significantly lower their average impact ve-375 locity when online sonification was present, but not their variability. Golf research suggests 376 swing timing is a significant factor that contributes to the success of a putt [5,26], which [8] 377 found to be strongly correlated to impact velocity. More specifically, our findings suggest 378 online sonification played a role in modifying swing timing or acceleration profiles, which 379 in turn caused participants to affectively lower their impact velocity. Although their impact 380 velocities appeared to be affected by sonification, because no sound synthesis parameter 381 emerged as significantly different suggests participants were unaffected by the timbral dif-382 ferences between the sounds. This is an interesting observation with regards to distinctions 383

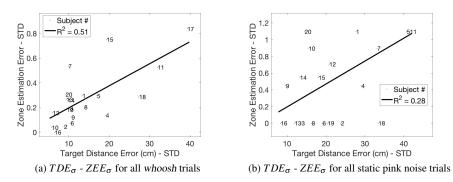


Fig. 3  $R^2$  correlations between Target Distance Error standard deviation ( $TDE_{\sigma}$ ) and Zone Estimation Error standard deviation ( $ZEE_{\sigma}$ ) for trials with the whoosh synthesiser,  $R^2 = 0.51$ , p < 0.001 (a) and static pink noise,  $R^2 = 0.28$ , p < 0.05 (b).

made in the auditory system, which demands further study. Although we did not test all possible sound configurations, it is possible that participants might have found some sounds to
be more efficient. That said, this was not the goal of our study but rather whether participants
were able to extract information (club head speed) from the presented sounds.

Using linear regression models, we found average impact velocity correlated poorly to 388 target distance error standard deviation ( $R^2 = 0.02$ , p > 0.05) and zone estimation error 389 standard deviations ( $R^2 < 0.01$ , p > 0.05) during whoosh synthesiser trials. Similarly we 390 found that during static pink noise trials, average impact velocity correlated poorly to target 391 distance error standard deviation ( $R^2 = 0.12$ , p > 0.05) and zone estimation error standard 392 deviation ( $R^2 = 0.02$ , p > 0.05). These results suggest that the sound of impact did not play 393 an important role when participants made performance-based estimations. Of course one 394 way to verify this would be to sonify the moment of impact with the ball. If we masked 395 the sound of contact with the ball by exaggerating or minimising the presence of natural 396 acoustic feedback [36], we might examine the effects on performance. 397

However, [35] reported strong correlations between performance and subjective percep-398 tions based on impact sound for elite golfers. One might then hypothesise that a "good" 399 impact sound would motivate players to maintain or continue executing the complex motor 400 task, whereas a "bad" sound would encourage them to make adjustments to their swings. Of 401 course an impact sound is a short impulse that follows the execution of a complex move-402 ment (Appendix 2), whereas the sonifications provided to our participants are based on this 403 gesture and display each unique history. Because participants offered their estimations after 404 making impact, our significant findings for target distance error and zone estimation error 405 standard deviations reinforce the influence of sonification on behavioural performance and 406 perceptual correlates. 407

Reflecting on our testing and analysis, we acknowledge that studying the effects of 24 408 different sonifications developed from combinations of types of synthesisers, modulations, 409 scales, and mappings was ambitious. In some part this was due to our implementation of 410 sonification parameters that were dependent on our synthesiser design. However, studying 411 and reporting on them are important contributions to help researchers identify which sound 412 synthesis parameters and combinations can affect performance and perceptual correlates. 413 Moreover, our findings revealed that some parameters could be varied in ways that affected 414 behavioural and perceptual performance differently. As previously discussed, a major take 415

away was that while participants reduced their target distance error standard deviation when 416 either synthesiser was present, only the whoosh synthesiser led them to significantly reduce 417 their zone estimation error variability when compared to trials associated with the jet syn-418 thesiser and static pink noise. That being the case, our findings also showed the whoosh 419 synthesiser, when its scale was limited (1:1), interacted with all other mappings to produce 420 significant differences in target distance error standard deviation when compared to static 421 pink noise. Here we observed that only the combination of whoosh \* 1:1 scale yielded sig-422 nificant differences when compared to static pink noise, which suggests participants had 423 greater difficulty using sounds where club head speed was mapped onto a greater range. 424 Although no mapping type distinguished itself from another, we did observe a more pro-425 nounced effect with linear mapping (around 2 cm). Taken together these findings suggest 426 participants found sounds generated by the whoosh synthesiser easier to use to enhance be-427 havioural and perceptual performance. Nevertheless these different combinations permitted 428 us to observe different effects.

#### 430 4.1 Conclusion

The results of this study demonstrate that novices were able to use sound to reduce performance variability while completing a complex motor task. A major highlight of these significant findings was that participants were not required to synchronise or conform their movements to the sound presented to them. Concurrent sound enhanced their natural execution of the swing gesture, a point advocated by [13].

Based on our target distance error and zone estimation error standard deviation results, one could propose the use of auditory feedback to lower variability in executing complex motor skills. For example, [24] found they were able to lower variability in professional woman golf players by using neural networks to develop training exercises based on previous training trials. One might imagine auditory feedback could be developed in a way that considers the unique features of the novice participant while minimising the factors that deviate from their average or optimal swing form.

Motivated by this proposition, we recently finished a new golf putting study where au-443 ditory feedback was developed and dedicated to giving information based on the real-time 444 comparison between optimal and observed swings [33]. Following a number of success-445 ful trials, we identified unique characteristics in their swings and used this information to 446 develop participant-dependent swing models that could be used to compare and calculate 447 real-time differences for each swing. These differences were then sonified in different ways 448 and presented to participants. Based on results from [47], we believed that this type of error-449 based personalised sonification might help novices reduce movement variability, which, in 450 turn, might affect and effectively optimise their performance. Although a comprehensive 451 report of our findings is forthcoming, the initial results suggest that participants who experi-452 enced a specific type of online auditory feedback significantly reduced movement variability. 453

#### 454 Funding

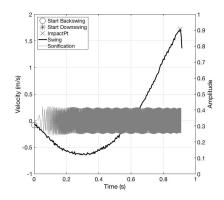
<sup>455</sup> This work was funded by the French National Research Agency (ANR) under the SoniMove:

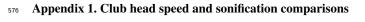
<sup>456</sup> Inform, Guide and Learn Actions by Sounds project (ANR-14-CE24-0018-01).

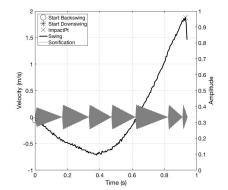
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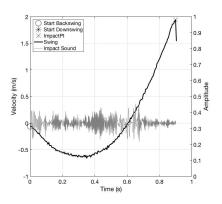


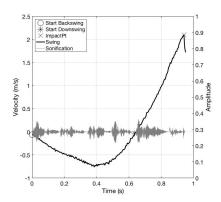




(b) jet \* rhythmicity \* scale 1:2 \* linear mapping

(a) *jet* \* brightness \* scale 1:2 \* linear mapping





(c) whoosh \* brightness \* scale 1:2 \* linear mapping

(d) whoosh \* rhythmicity \* scale 1:2 \* linear mapping

**Fig. 4** Comparison of participant performing golf putting task with different club head speeds and the auditory signals generated from them. The following sound synthesis combinations were used, where scale 1:2 and linear mapping were fixed: *jet* \* brightness (a); *jet* \* rhythmicity (b); *whoosh* \* brightness (c); and *whoosh* \* rhythmicity (d).

#### 577 Appendix 2. Impact sound and static pink noise

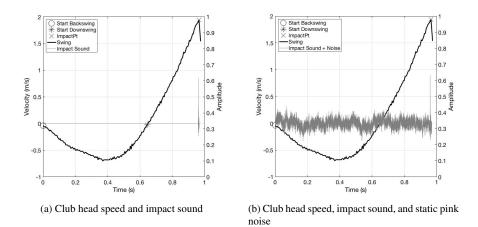


Fig. 5 Participant performing putting task without (a) and with (b) static pink noise.