

Hand Trajectory Analysis in the Study of Premotor Activity: An Exploration

Bolger Deirdre, Mestre Daniel, Jean-Marie Pergandi, Zappa Ana,

Frenck-Mestre Cheryl

▶ To cite this version:

Bolger Deirdre, Mestre Daniel, Jean-Marie Pergandi, Zappa Ana, Frenck-Mestre Cheryl. Hand Trajectory Analysis in the Study of Premotor Activity: An Exploration. Retraite ILCB/BLRI Porquerolles, May 2019, Porquerolles, France. hal-03992695

HAL Id: hal-03992695 https://amu.hal.science/hal-03992695

Submitted on 16 Feb 2023 $\,$

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Hand Trajectory Analysis in the Study of Premotor Activity: An Exploration

Bolger Deirdre, Mestre Daniel, Pergandi Jean-Marie, Zappa Ana and Frenck-Mestre Cheryl

Institute of Language, Communication and the Brain (ILCB), Centre de Réalité Virtuelle de la Méditerranée (CRVM), Laboratoire de Parole et Langage (LPL)

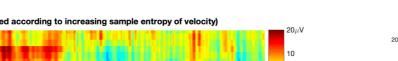
Introduction

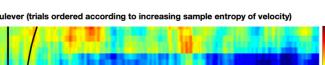
- Here we present a first step in the exploration of the use of movement trajectory data in single-trial EEG analysis, based on the hypothesis that certain features of the actual movement to be executed may be reflected in premotor activity and characterising these features may assist the study of premotor activity at a single-trial basis.
- Research has posited that a trajectory-path representation may be used to plan reaching and grasping gestures (Wong et al, 2016).
- Activity in dorsal pre-motor and motor cortices and the SMA has been linked to planning high level kinematic parameters such as **movement** direction, amplitude and speed in reaching and grasping actions (Pearse and

Complexity Measure

- **Sample Entropy** is the negative natural logarithm of the conditional probability that two sequences similar for *m* points will remain so at the next point.
- A lower sample entropy of a given time-series implies greater self-similarity.
- ► It is relatively stable as a function of time-series length.
- Calculation of time-dependent sample entropy of velocity, acceleration and straightness from 0.5 of time-series duration (Li et al, 2014).

Total Sample Entropy in Single-trial Analysis







Moran, 2012, Torres et al, 2013).

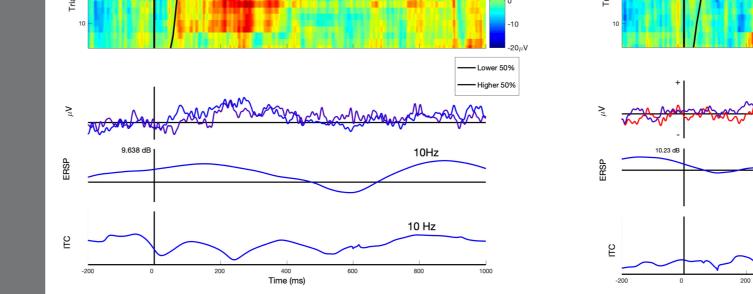
Hypotheses

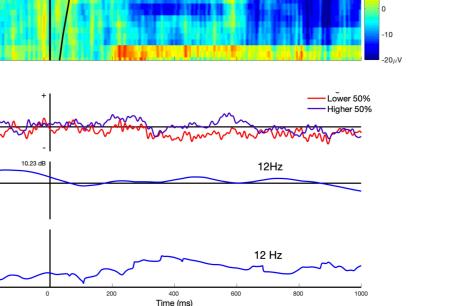
- The relative **complexity** of a planned movement trajectory may be reflected in pre-motor activity \implies quantify trajectory complexity at the single trial level to refine analysis of pre-motor activity.
- \blacktriangleright If kinematic features are planned prior to action \implies characterise the **General Movement Features** (Li et al, 2014) of the trajectory.
- \blacktriangleright if a less complex action is less prone to variation \implies calculate the distance between different instances of the same movement.
- Use complexity measure (sample entropy) as regressor in single trial analysis.
- ► Group single trials based on analysis of *distance* between the complexity, over time, of different instances of an action.

Data Acquisition

► Hand movement data was acquired via a wireless finger-tracking device (ART: Advanced Realtime Tracking) that tracks, in real time, the orientation and position of the hand and fingers during a GO-NOGO protocol in a fully immersive VR environment.

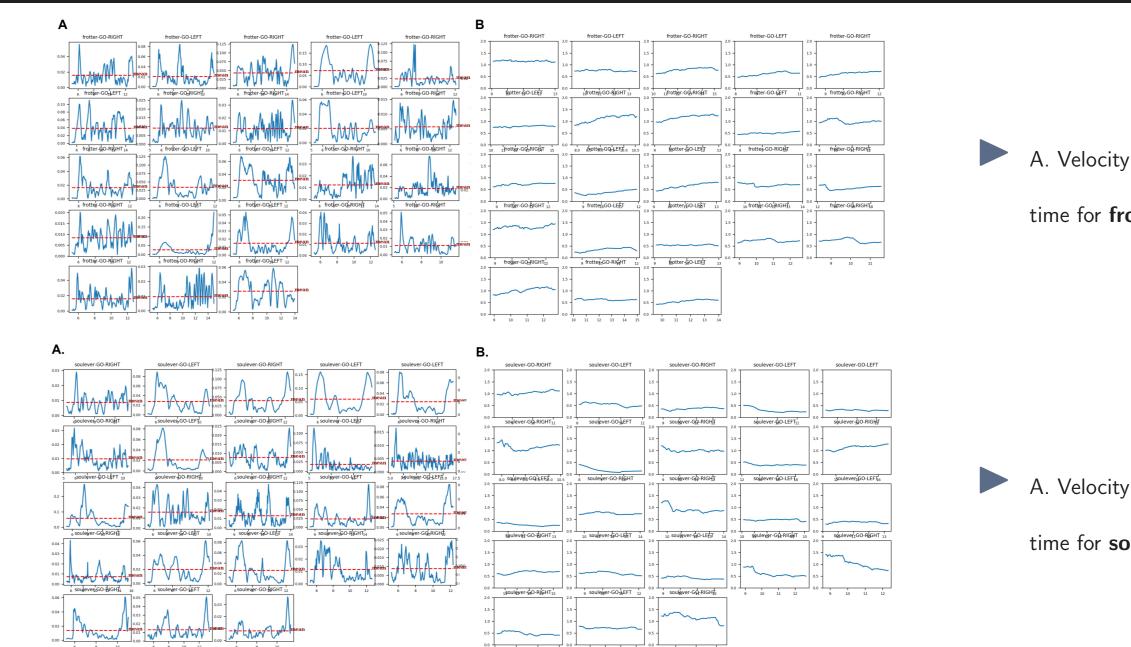






trials ordered according to increasing **sample** entropy (black line) for (left) **frotter** and (right) **soulever**.

General Movement Features and Sample Entropy



A. Velocity over time and B. Sample Entropy over

time for **frotter**

A. Velocity over time and B. Sample Entropy over

time for **soulever**

Figure 1: Participant with finger-tracking device manipulating virtual object.

Trajectory Representation

Trajectory: the path of a moving object composed of quasi-linear segments at which points are attributed spatial and temporal information e.g. $\{X_t, Y_t, Z_t\}$. ► The trajectories, below, are based on a subset of single GO trials over 14 participants.

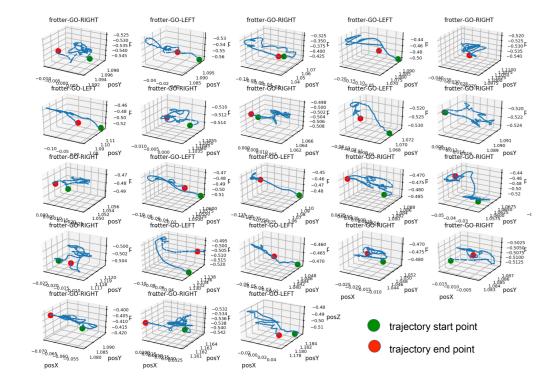


Figure 2: Quiver plot of X, Y, Z hand trajectory of action **frotter**

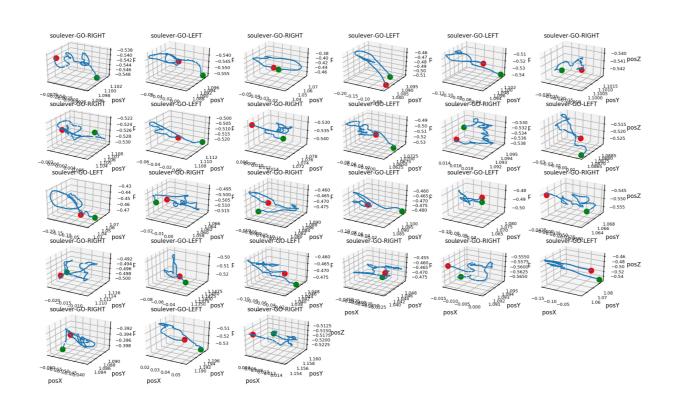
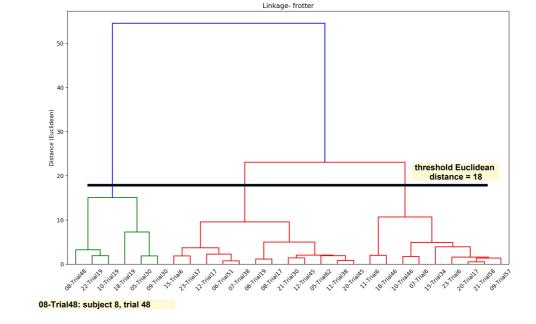


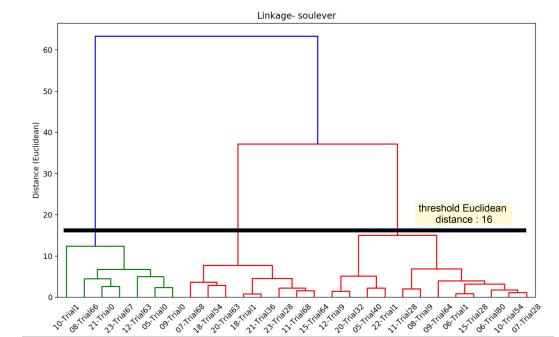
Figure 3: Quiver plot of trajectory of action **soulever**.

General Movement Trajectory Features

Velocity Dis/Similarity Calculation

► With the aim of grouping trials based on the complexity of the movement features, we applied Hierarchical Clustering on the sample entropy of the velocity. **Dynamic Time Warping** was applied to compute the cross-similarity matrix ; the distance metric applied is the Euclidean distance.





- The result of the hierarchical clustering can indicate the number of clusters and a minimum inter-cluster distance for subsequent clustering algorithms, such as Kmeans clustering.
- ► The dendogram for **frotter** (left) suggests 3 clusters and an inter-cluster distance of 18.

To be continued...

Here we present a very first step in this work. Some of the issues that need to be tackled include:

Velocity: Rate of location change from the previous time point to the next.

 $Velocity_{p_i,t_i} = \frac{distance(p_{i+1})}{\Delta_{t_i}}$

Acceleration: Rate of velocity change from the previous time step.

Acceleration_{p_i,t_i} = $\frac{Velocity(p_{i+1}, p_i)}{\Delta_{t_i}}$

Straightness Index: The ratio of the length of two consecutive trajectory segments and the displacement from the start of the first segment to the end of the second.

 $Straightness_{p_i,t_i} = \frac{distance(p_i - 1, p_i) + distance(p_i, p_{i+1})}{distance(p_{i-1}, p_{i+1})}$

Where p_i is the sampling point at time *i*.

ILCB, CRVM, LPL 2019

- Test other movement features and means of characterising the trajectory data to determine those descriptors that best capture pre-motor activity variation across trials.
- Calculate sample entropy of other movement features and of the trajectory.
- Test clustering methods (Kmeans, Self-organising maps) to group hand trajectories according to different features that may refine single-trial analysis.

Bibliography

- Chen, W., Zhuang, J., Yu, W., & Wang, Z. (2009). Measuring complexity using FuzzyEn, ApEn, and SampEn. Medical Engineering and Physics, 31(1), 6168.
- ▶ Li, X., & Li, X. (2014). Using Complexity Measures of Movement for Automatically Detecting Movement Types of Unknown GPS Trajectories. American Journal of Geographic Information System, 3(2), 6374.
- Pearce, T. M., & Moran, D. W. (2012). Strategy-dependent encoding of dorsal premotor cortex. Science, 337(August), 984988.
- ▶ Richman, J. S., & Moorman, J. R. (2000). Physiological time-series analysis using approximate entropy and sample entropy. American Journal of Physiology. Heart and Circulatory Physiology.
- ► Torres, E. B., Quian Quiroga, R., Cui, H., & Buneo, C. A. (2013). Neural correlates of learning and trajectory planning in the posterior parietal cortex. Frontiers in Integrative Neuroscience, 7(May), 1 20.
- ▶ Wong, A. L., Jax, S. A., Smith, L. L., Buxbaum, L. J., & Krakauer, J. W. (2019). Movement imitation via an abstract trajectory representation in dorsal premotor cortex. The Journal of Neuroscience, 2597-18.